
Dielectric Tensor - Cold plasma

08-06-16

N. T. Gladd

Initialization: Be sure the files *NTGStylesheet2.nb* and *NTGUtilityFunctions.m* is are in the same directory as that from which this notebook was loaded. Then execute the cell immediately below by mousing left on the cell bar to the right of that cell and then typing “shift” + “enter”. Respond “Yes” in response to the query to evaluate initialization cells.

In[28]:=

```
SetDirectory[NotebookDirectory[]];
(* set directory where source files are located *)
SetOptions[EvaluationNotebook[], (* load the StyleSheet *)
  StyleDefinitions -> Get["NTGStylesheet2.nb"]];
Get["NTGUtilityFunctions.m"]; (* Load utilities package *)
```

Original notes *Dielectric Tensor - Cold plasma 05-24-15* (also many other times, starting circa 1968)

Purpose

I use Mathematica to derive the dielectric tensor for a cold magnetized plasma, a structure used when analyzing the properties of waves that exist in this plasma. This derivation is a right of passage for students of plasma physics.

My primary interest in this series of notebooks is illustrate how Mathematica can be used to facilitate the mathematical operations involved in plasma derivations and calculations. Development of the framework for analyzing waves in a cold magnetized plasma case serves well as a basic template for more complex examples. I won't discuss the underlying physics, most texts on plasmas cover this topic. My favorite is still the text from which I learned *Principles of Plasma Physics*, N. A. Krall and A. W. Trivelpiece for plasmas, coauthored by my friend, mentor and former boss Nick Krall.

See <https://arxiv.org/pdf/physics/0701257v1.pdf> for the treatment of a similar problem using a different Mathematica programming style.

Derivation of the cold plasma dielectric tensor is rather straightforward. In a subsequent notebook, I will repeat the derivation of the dielectric tensor using kinetic theory, in which case the calculation is considerable more involved.

Dispersion equation and dielectric tensor

Consider Ampere's law and Faraday's law in Gaussian notation

$$\nabla \times \vec{B}(\vec{x}, t) = \frac{4\pi}{c} \vec{j}(\vec{x}, t) + \frac{1}{c} \frac{\partial \vec{E}(\vec{x}, t)}{\partial t} \quad (1)$$

$$\nabla \times \vec{E}(\vec{x}, t) = -\frac{1}{c} \frac{\partial \vec{B}(\vec{x}, t)}{\partial t} \quad (2)$$

The current \vec{j} is assumed to be related to the electric field through a conductivity tensor $\vec{\sigma}$

$$\vec{j} = \vec{\sigma} \cdot \vec{E} \quad (3)$$

Under the assumption of plane-wave waves, these three equations can be used to derive the expression

$$\vec{\mathcal{D}} \cdot \vec{E} = 0 \quad (4)$$

The dispersive properties of waves are described by the expression

$$\det(\vec{\mathcal{D}}) = 0 \quad (5)$$

The first derivation below will consist of using Mathematica methods to derive the matrix \mathcal{D} . Along the way, the dielectric tensor

$$\vec{\epsilon} = \left(\vec{1} + \frac{4\pi i}{\omega} \vec{\sigma} \right) \quad (6)$$

is identified.

The explicit form for \mathcal{D} derived below in Section 1 is (w1[6])

$$\vec{\mathcal{D}} = \begin{pmatrix} \mathbf{1} - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{x,x} & \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{x,y} & \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{x,z} \\ \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{y,x} & \mathbf{1} - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{y,y} & \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{y,z} \\ \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{z,x} & \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{z,y} & \mathbf{1} - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{z,z} \end{pmatrix}$$

The second calculation will assume a uniform plasma embedded in a constant unidirectional magnetic field. In the limit of a cold fluid plasma, the specific expressions for the elements of the conductivity and dielectric tensors are derived.

For the cold fluid plasma, the starting equations are continuity

$$\frac{\partial n(\vec{x}, t)}{\partial t} + \nabla \cdot (n(\vec{x}, t) \vec{v}(\vec{x}, t)) = 0 \quad (7)$$

and motion

$$m n(\vec{x}, t) \frac{d \vec{v}(\vec{x}, t)}{dt} = q n(\vec{x}, t) \left(\vec{E}(\vec{x}, t) + \frac{\vec{v}(\vec{x}, t) \times \vec{B}(\vec{x}, t)}{c} \right) \quad (8)$$

The explicit form for the dielectric tensor derived below in Section 2 is `w2["dielectric tensor"]`[1]

$$\vec{\epsilon} = \begin{pmatrix} 1 - \frac{\omega \omega_p^2}{\omega^3 - \omega \omega_c^2} & -\frac{i \omega_c \omega_p^2}{\omega^3 - \omega \omega_c^2} & 0 \\ \frac{i \omega_c \omega_p^2}{\omega^3 - \omega \omega_c^2} & 1 - \frac{\omega \omega_p^2}{\omega^3 - \omega \omega_c^2} & 0 \\ 0 & 0 & 1 - \frac{\omega_p^2}{\omega^2} \end{pmatrix}$$

Mathematica preliminaries

I predefine a number of Mathematica functions and rules

`MakeScalar`, `MakeVector`, `GenerateComponentEquations`, `perturbationRules`, `equilibriumRules`, `LinearizeEquation`, `Eikonal`, `MakeEikonalRule`, `ApplyEikonal`, `def[\omega_c]`, `def[\omega_p]`

These are defined below in Section **Functions**.

I Deriving the dispersion equation

Starting with Ampere's law (1) and Faraday's law (1), I derive the dispersion equation for plane wave perturbations of a uniform plasma in a constant magnetic field

In[30]= `w1["Ampere"] [1] = Inactivate[Curl[B, {x, y, z}] == $\frac{4 \pi}{c} \mathbf{j} + \frac{1}{c} \mathbf{D}[\epsilon, t], \text{Curl} | \mathbf{D}]$`

Out[30]= $\nabla_{\{x, y, z\}} \times \mathcal{B} == \frac{4 \mathbf{j} \pi}{c} + \frac{\partial_t \epsilon}{c}$

I perform operations that transform this high level representation of Ampere's law into a form from which calculations can be performed. The function `Inactivate` temporarily prevents the functions `Curl` and `D` from evaluating. The first step is to introduce explicit time and space dependence.

In[31]= `w1["Ampere"] [2] = w1["Ampere"] [1] /. (MakeVector /@ {B, \partial_t \epsilon, j})`

Out[31]= $\nabla_{\{x, y, z\}} \times \{ \mathcal{B}_x[x, y, z, t], \mathcal{B}_y[x, y, z, t], \mathcal{B}_z[x, y, z, t] \} ==$

$$\left\{ \frac{\partial_t \epsilon_x[x, y, z, t]}{c} + \frac{4 \pi \mathbf{j}_x[x, y, z, t]}{c}, \right.$$

$$\left. \frac{\partial_t \epsilon_y[x, y, z, t]}{c} + \frac{4 \pi \mathbf{j}_y[x, y, z, t]}{c}, \frac{\partial_t \epsilon_z[x, y, z, t]}{c} + \frac{4 \pi \mathbf{j}_z[x, y, z, t]}{c} \right\}$$

With explicit space and time dependence established, the operators can be "activated."

In[32]=

```
w1["Ampere"][3] = w1["Ampere"][2] // Activate[#, Curl | D] &
```

Out[32]=

$$\left\{ -\mathcal{B}_y^{(0,0,1,0)}[x, y, z, t] + \mathcal{B}_z^{(0,1,0,0)}[x, y, z, t], \mathcal{B}_x^{(0,0,1,0)}[x, y, z, t] - \mathcal{B}_z^{(1,0,0,0)}[x, y, z, t], \right. \\ \left. -\mathcal{B}_x^{(0,1,0,0)}[x, y, z, t] + \mathcal{B}_y^{(1,0,0,0)}[x, y, z, t] \right\} == \\ \left\{ \frac{4\pi j_x[x, y, z, t]}{c} + \frac{\varepsilon_x^{(0,0,0,1)}[x, y, z, t]}{c}, \frac{4\pi j_y[x, y, z, t]}{c} + \frac{\varepsilon_y^{(0,0,0,1)}[x, y, z, t]}{c}, \right. \\ \left. \frac{4\pi j_z[x, y, z, t]}{c} + \frac{\varepsilon_z^{(0,0,0,1)}[x, y, z, t]}{c} \right\}$$

The operators expanded into the form of a $\{\text{lhs}_1, \text{lhs}_2, \dots\} == \{\text{rhs}_1, \text{rhs}_2, \dots\}$. The function *GenerateComponentEquations* transforms the resulting expression into a list of equations $\{\text{lhs}_1 == \text{rhs}_1, \text{lhs}_2 == \text{rhs}_2, \dots\}$.

In[33]=

```
w1["Ampere"][4] = w1["Ampere"][3] // GenerateComponentEquations
```

Out[33]=

$$\left\{ -\mathcal{B}_y^{(0,0,1,0)}[x, y, z, t] + \mathcal{B}_z^{(0,1,0,0)}[x, y, z, t] == \frac{4\pi j_x[x, y, z, t]}{c} + \frac{\varepsilon_x^{(0,0,0,1)}[x, y, z, t]}{c}, \right. \\ \mathcal{B}_x^{(0,0,1,0)}[x, y, z, t] - \mathcal{B}_z^{(1,0,0,0)}[x, y, z, t] == \frac{4\pi j_y[x, y, z, t]}{c} + \frac{\varepsilon_y^{(0,0,0,1)}[x, y, z, t]}{c}, \\ \left. -\mathcal{B}_x^{(0,1,0,0)}[x, y, z, t] + \mathcal{B}_y^{(1,0,0,0)}[x, y, z, t] == \frac{4\pi j_z[x, y, z, t]}{c} + \frac{\varepsilon_z^{(0,0,0,1)}[x, y, z, t]}{c} \right\}$$

I perturb these equations using rules of the type (see *perturbationRules* in *Functions* section below)

$$n \rightarrow n_0 + \varepsilon \delta n(x, y, z, t)$$

$$v_x \rightarrow v_{x0} + \varepsilon \delta v_x(x, y, z, t), \quad v_y \rightarrow v_{y0} + \varepsilon \delta v_y(x, y, z, t), \quad v_z \rightarrow v_{z0} + \varepsilon \delta v_z(x, y, z, t)$$

...

and impose the conditions of no equilibrium flows, currents, electric field, and uniform magnetic field on the equilibrium state (see *equilibriumRules* in *Functions* section below).

The imposition of these rules leads to

In[34]=

```
w1["Ampere"][5] = w1["Ampere"][4] /. perturbationRules /. equilibriumRules
```

Out[34]=

$$\left\{ -\varepsilon \delta \mathcal{B}_y^{(0,0,1,0)}[x, y, z, t] + \varepsilon \delta \mathcal{B}_z^{(0,1,0,0)}[x, y, z, t] == \right. \\ \left. \frac{4\pi \varepsilon \delta j_x[x, y, z, t]}{c} + \frac{\varepsilon \delta \varepsilon_x^{(0,0,0,1)}[x, y, z, t]}{c}, \right. \\ \varepsilon \delta \mathcal{B}_x^{(0,0,1,0)}[x, y, z, t] - \varepsilon \delta \mathcal{B}_z^{(1,0,0,0)}[x, y, z, t] == \\ \left. \frac{4\pi \varepsilon \delta j_y[x, y, z, t]}{c} + \frac{\varepsilon \delta \varepsilon_y^{(0,0,0,1)}[x, y, z, t]}{c}, \right. \\ -\varepsilon \delta \mathcal{B}_x^{(0,1,0,0)}[x, y, z, t] + \varepsilon \delta \mathcal{B}_y^{(1,0,0,0)}[x, y, z, t] == \\ \left. \frac{4\pi \varepsilon \delta j_z[x, y, z, t]}{c} + \frac{\varepsilon \delta \varepsilon_z^{(0,0,0,1)}[x, y, z, t]}{c} \right\}$$

Linearize the equations

In[35]=

```
w1["Ampere"][6] = w1["Ampere"][5] // LinearizeEquation
```

Out[35]=

$$\left\{ \begin{aligned} -\delta\mathcal{B}_y^{(0,0,1,0)}[x, y, z, t] + \delta\mathcal{B}_z^{(0,1,0,0)}[x, y, z, t] &= \\ \frac{4\pi\delta\hat{j}_x[x, y, z, t]}{c} + \frac{\delta\mathcal{E}_x^{(0,0,0,1)}[x, y, z, t]}{c}, \\ \delta\mathcal{B}_x^{(0,0,1,0)}[x, y, z, t] - \delta\mathcal{B}_z^{(1,0,0,0)}[x, y, z, t] &= \\ \frac{4\pi\delta\hat{j}_y[x, y, z, t]}{c} + \frac{\delta\mathcal{E}_y^{(0,0,0,1)}[x, y, z, t]}{c}, \\ -\delta\mathcal{B}_x^{(0,1,0,0)}[x, y, z, t] + \delta\mathcal{B}_y^{(1,0,0,0)}[x, y, z, t] &= \\ \frac{4\pi\delta\hat{j}_z[x, y, z, t]}{c} + \frac{\delta\mathcal{E}_z^{(0,0,0,1)}[x, y, z, t]}{c} \end{aligned} \right\}$$

and apply a plane wave eikonal. For example,

$$\delta\mathbf{j}_x(\vec{x}, t) = \delta\mathbf{j}_x(\vec{k}, \omega) e^{i(\vec{k}\cdot\vec{x} - \omega t)} = \hat{\delta}\mathbf{j}_x e^{i(\vec{k}\cdot\vec{x} - \omega t)}$$

In[36]=

```
w1["Ampere"][7] = w1["Ampere"][6] // ApplyEikonal
```

Out[36]=

$$\left\{ \begin{aligned} \delta\hat{\mathcal{B}}_z k_y - \delta\hat{\mathcal{B}}_y k_z &= -\frac{4\hat{i}\pi\delta\hat{j}_x}{c} - \frac{\omega\delta\hat{\mathcal{E}}_x}{c}, \\ -\delta\hat{\mathcal{B}}_z k_x + \delta\hat{\mathcal{B}}_x k_z &= -\frac{4\hat{i}\pi\delta\hat{j}_y}{c} - \frac{\omega\delta\hat{\mathcal{E}}_y}{c}, \\ \delta\hat{\mathcal{B}}_y k_x - \delta\hat{\mathcal{B}}_x k_y &= -\frac{4\hat{i}\pi\delta\hat{j}_z}{c} - \frac{\omega\delta\hat{\mathcal{E}}_z}{c} \end{aligned} \right\}$$

The same procedure is used for Faraday's law.

In[37]=

```
w1["Faraday"][1] = Inactivate[Curl[ε, {x, y, z}] == -1/c D[B, t], Curl | D]
```

Out[37]=

$$\nabla_{\{x,y,z\}} \times \mathcal{E} = -\frac{\partial_t \mathcal{B}}{c}$$

Having shown the details for Ampere, I can streamline the analogous calculation for Faraday

In[38]=

```
w1["Faraday"][2] = w1["Faraday"][1] /. (MakeVector /@ {ε, ∂tB}) // Activate[#, Curl | D] & // GenerateComponentEquations
```

Out[38]=

$$\left\{ \begin{aligned} -\mathcal{E}_y^{(0,0,1,0)}[x, y, z, t] + \mathcal{E}_z^{(0,1,0,0)}[x, y, z, t] &= -\frac{\mathcal{B}_x^{(0,0,0,1)}[x, y, z, t]}{c}, \\ \mathcal{E}_x^{(0,0,1,0)}[x, y, z, t] - \mathcal{E}_z^{(1,0,0,0)}[x, y, z, t] &= -\frac{\mathcal{B}_y^{(0,0,0,1)}[x, y, z, t]}{c}, \\ -\mathcal{E}_x^{(0,1,0,0)}[x, y, z, t] + \mathcal{E}_y^{(1,0,0,0)}[x, y, z, t] &= -\frac{\mathcal{B}_z^{(0,0,0,1)}[x, y, z, t]}{c} \end{aligned} \right\}$$

In[39]=

```
w1["Faraday"][3] =
w1["Faraday"][2] /. perturbationRules /. equilibriumRules // LinearizeEquation //
ApplyEikonal
```

Out[39]=

$$\left\{ \delta \hat{\mathcal{E}}_z k_y - \delta \hat{\mathcal{E}}_y k_z = \frac{\omega \delta \hat{\mathcal{B}}_x}{c}, -\delta \hat{\mathcal{E}}_z k_x + \delta \hat{\mathcal{E}}_x k_z = \frac{\omega \delta \hat{\mathcal{B}}_y}{c}, \delta \hat{\mathcal{E}}_y k_x - \delta \hat{\mathcal{E}}_x k_y = \frac{\omega \delta \hat{\mathcal{B}}_z}{c} \right\}$$

Proceeding

In[40]=

```
w1[1] = Solve[w1["Faraday"][3], {\delta \hat{\mathcal{B}}_x, \delta \hat{\mathcal{B}}_y, \delta \hat{\mathcal{B}}_z}][[1]]
```

Out[40]=

$$\left\{ \delta \hat{\mathcal{B}}_x \rightarrow \frac{c (\delta \hat{\mathcal{E}}_z k_y - \delta \hat{\mathcal{E}}_y k_z)}{\omega}, \delta \hat{\mathcal{B}}_y \rightarrow -\frac{c (\delta \hat{\mathcal{E}}_z k_x - \delta \hat{\mathcal{E}}_x k_z)}{\omega}, \delta \hat{\mathcal{B}}_z \rightarrow \frac{c (\delta \hat{\mathcal{E}}_y k_x - \delta \hat{\mathcal{E}}_x k_y)}{\omega} \right\}$$

Use these rules to eliminate $\delta \hat{\mathcal{B}}$ from Ampere's law

In[41]=

```
w1[2] = w1["Ampere"][7] /. w1[1] /. a_ == b_ -> a - b == 0
```

Out[41]=

$$\left\{ \begin{aligned} \frac{4 i \pi \delta \hat{\mathcal{J}}_x}{c} + \frac{\omega \delta \hat{\mathcal{E}}_x}{c} + \frac{c k_y (\delta \hat{\mathcal{E}}_y k_x - \delta \hat{\mathcal{E}}_x k_y)}{\omega} + \frac{c k_z (\delta \hat{\mathcal{E}}_z k_x - \delta \hat{\mathcal{E}}_x k_z)}{\omega} &= 0, \\ \frac{4 i \pi \delta \hat{\mathcal{J}}_y}{c} + \frac{\omega \delta \hat{\mathcal{E}}_y}{c} - \frac{c k_x (\delta \hat{\mathcal{E}}_y k_x - \delta \hat{\mathcal{E}}_x k_y)}{\omega} + \frac{c k_z (\delta \hat{\mathcal{E}}_z k_y - \delta \hat{\mathcal{E}}_y k_z)}{\omega} &= 0, \\ \frac{4 i \pi \delta \hat{\mathcal{J}}_z}{c} + \frac{\omega \delta \hat{\mathcal{E}}_z}{c} - \frac{c k_x (\delta \hat{\mathcal{E}}_z k_x - \delta \hat{\mathcal{E}}_x k_z)}{\omega} - \frac{c k_y (\delta \hat{\mathcal{E}}_z k_y - \delta \hat{\mathcal{E}}_y k_z)}{\omega} &= 0 \end{aligned} \right\}$$

I simplify this expression

In[42]=

```
w1[3] = MapEqn[(Expand[# c / \omega]) &, w1[2]]
```

Out[42]=

$$\left\{ \begin{aligned} \frac{4 i \pi \delta \hat{\mathcal{J}}_x}{\omega} + \delta \hat{\mathcal{E}}_x + \frac{c^2 \delta \hat{\mathcal{E}}_y k_x k_y}{\omega^2} - \frac{c^2 \delta \hat{\mathcal{E}}_x k_y^2}{\omega^2} + \frac{c^2 \delta \hat{\mathcal{E}}_z k_x k_z}{\omega^2} - \frac{c^2 \delta \hat{\mathcal{E}}_x k_z^2}{\omega^2} &= 0, \\ \frac{4 i \pi \delta \hat{\mathcal{J}}_y}{\omega} + \delta \hat{\mathcal{E}}_y - \frac{c^2 \delta \hat{\mathcal{E}}_y k_x^2}{\omega^2} + \frac{c^2 \delta \hat{\mathcal{E}}_x k_x k_y}{\omega^2} + \frac{c^2 \delta \hat{\mathcal{E}}_z k_y k_z}{\omega^2} - \frac{c^2 \delta \hat{\mathcal{E}}_y k_z^2}{\omega^2} &= 0, \\ \frac{4 i \pi \delta \hat{\mathcal{J}}_z}{\omega} + \delta \hat{\mathcal{E}}_z - \frac{c^2 \delta \hat{\mathcal{E}}_z k_x^2}{\omega^2} - \frac{c^2 \delta \hat{\mathcal{E}}_z k_y^2}{\omega^2} + \frac{c^2 \delta \hat{\mathcal{E}}_x k_x k_z}{\omega^2} + \frac{c^2 \delta \hat{\mathcal{E}}_y k_y k_z}{\omega^2} &= 0 \end{aligned} \right\}$$

and introduce the conductivity tensor via $\vec{\delta \mathcal{J}} = \hat{\sigma} \cdot \vec{\delta \mathcal{E}}$

In[43]=

```
conductivityRule = \delta \hat{\mathcal{J}}_{a\_} \rightarrow \sigma_{a,x} \delta \hat{\mathcal{E}}_x + \sigma_{a,y} \delta \hat{\mathcal{E}}_y + \sigma_{a,z} \delta \hat{\mathcal{E}}_z
```

Out[43]=

$$\delta \hat{\mathcal{J}}_{a_} \rightarrow \delta \hat{\mathcal{E}}_x \sigma_{a,x} + \delta \hat{\mathcal{E}}_y \sigma_{a,y} + \delta \hat{\mathcal{E}}_z \sigma_{a,z}$$

In[44]:=

w1[4] = w1[3] /. conductivityRule // ExpandAll

Out[44]=

$$\left\{ \delta \hat{\epsilon}_x + \frac{c^2 \delta \hat{\epsilon}_y k_x k_y}{\omega^2} - \frac{c^2 \delta \hat{\epsilon}_x k_y^2}{\omega^2} + \frac{c^2 \delta \hat{\epsilon}_z k_x k_z}{\omega^2} - \frac{c^2 \delta \hat{\epsilon}_x k_z^2}{\omega^2} + \frac{4 i \pi \delta \hat{\epsilon}_x \sigma_{x,x}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_y \sigma_{x,y}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_z \sigma_{x,z}}{\omega} = 0, \right.$$

$$\delta \hat{\epsilon}_y - \frac{c^2 \delta \hat{\epsilon}_x k_x^2}{\omega^2} + \frac{c^2 \delta \hat{\epsilon}_x k_x k_y}{\omega^2} + \frac{c^2 \delta \hat{\epsilon}_z k_y k_z}{\omega^2} - \frac{c^2 \delta \hat{\epsilon}_y k_z^2}{\omega^2} + \frac{4 i \pi \delta \hat{\epsilon}_x \sigma_{y,x}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_y \sigma_{y,y}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_z \sigma_{y,z}}{\omega} = 0, \delta \hat{\epsilon}_z - \frac{c^2 \delta \hat{\epsilon}_z k_x^2}{\omega^2} - \frac{c^2 \delta \hat{\epsilon}_z k_y^2}{\omega^2} + \frac{c^2 \delta \hat{\epsilon}_x k_x k_z}{\omega^2} + \frac{c^2 \delta \hat{\epsilon}_y k_y k_z}{\omega^2} + \frac{4 i \pi \delta \hat{\epsilon}_x \sigma_{z,x}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_y \sigma_{z,y}}{\omega} + \frac{4 i \pi \delta \hat{\epsilon}_z \sigma_{z,z}}{\omega} = 0 \left. \right\}$$

Construct the elements of the matrix dispersion equation $\vec{\mathcal{D}} \cdot \vec{\delta E} = 0$

In[45]:=

**w1[5] = Table[
 Table[Coefficient[w1[4][[i, 1]], component], {component, {δ̂ε_x, δ̂ε_y, δ̂ε_z}}, {i, 1, 3}]**

Out[45]=

$$\left\{ \left\{ 1 - \frac{c^2 k_y^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \frac{4 i \pi \sigma_{x,x}}{\omega}, \frac{c^2 k_x k_y}{\omega^2} + \frac{4 i \pi \sigma_{x,y}}{\omega}, \frac{c^2 k_x k_z}{\omega^2} + \frac{4 i \pi \sigma_{x,z}}{\omega} \right\}, \right.$$

$$\left\{ \frac{c^2 k_x k_y}{\omega^2} + \frac{4 i \pi \sigma_{y,x}}{\omega}, 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \frac{4 i \pi \sigma_{y,y}}{\omega}, \frac{c^2 k_y k_z}{\omega^2} + \frac{4 i \pi \sigma_{y,z}}{\omega} \right\},$$

$$\left\{ \frac{c^2 k_x k_z}{\omega^2} + \frac{4 i \pi \sigma_{z,x}}{\omega}, \frac{c^2 k_y k_z}{\omega^2} + \frac{4 i \pi \sigma_{z,y}}{\omega}, 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_y^2}{\omega^2} + \frac{4 i \pi \sigma_{z,z}}{\omega} \right\} \left. \right\}$$

It is conventional to introduce the dielectric tensor $\hat{\epsilon} = 1 + \frac{4\pi i}{\omega} \hat{\sigma}$

In[46]:=

w1[6] = w1[5] /. $\frac{4 i \pi \sigma_{a,b}}{\omega} \rightarrow \epsilon_{a,b}$ - If[ToString[a] == ToString[b], 1, 0]

Out[46]=

$$\left\{ \left\{ 1 - \frac{c^2 k_y^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{x,x}, \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{x,y}, \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{x,z} \right\}, \right.$$

$$\left\{ \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{y,x}, 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{y,y}, \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{y,z} \right\},$$

$$\left\{ \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{z,x}, \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{z,y}, 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_y^2}{\omega^2} + \epsilon_{z,z} \right\} \left. \right\}$$

In[47]:=

w1[6] // MatrixForm

Out[47]/MatrixForm=

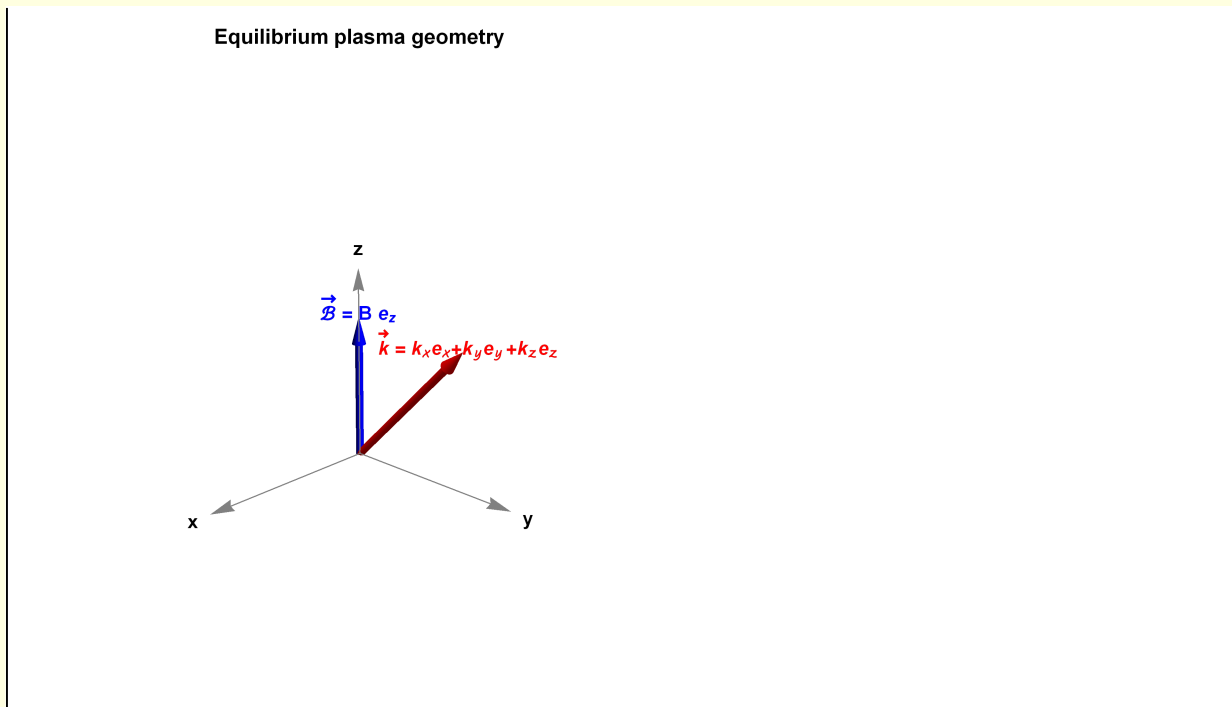
$$\begin{pmatrix} 1 - \frac{c^2 k_y^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{x,x} & \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{x,y} & \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{x,z} \\ \frac{c^2 k_x k_y}{\omega^2} + \epsilon_{y,x} & 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_z^2}{\omega^2} + \epsilon_{y,y} & \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{y,z} \\ \frac{c^2 k_x k_z}{\omega^2} + \epsilon_{z,x} & \frac{c^2 k_y k_z}{\omega^2} + \epsilon_{z,y} & 1 - \frac{c^2 k_x^2}{\omega^2} - \frac{c^2 k_y^2}{\omega^2} + \epsilon_{z,z} \end{pmatrix}$$

which is the desired result. The dielectric terms depend on the details of the plasma model. Also, any element of the dielectric tensor (or the equivalent conductivity tensor) implies a sum over each of the plasma species. Thus, for a plasma consisting of ions and electrons, the following interpretation is implied

$$\vec{\epsilon} \rightarrow \vec{\epsilon}_i + \vec{\epsilon}_e$$

2 Cold plasma modeled by fluid equations

A homogeneous cold plasma with a uniform magnetic field is assumed.



The continuity equation is processed first

```
In[48]:= w2["continuity"][1] = Inactivate[D[n, t] + Div[n v, {x, y, z}] == 0, D | Div]
```

```
Out[48]= ∂t n + ∇{x,y,z} · (n v) == 0
```

```
In[49]:= w2["continuity"][2] =  
w2["continuity"][1] /. {MakeScalar[n], MakeVector[v]} // Activate[#, D | Div] &
```

```
Out[49]= n(0,0,0,1)[x, y, z, t] +  
vz[x, y, z, t] n(0,0,1,0)[x, y, z, t] + n[x, y, z, t] vz(0,0,1,0)[x, y, z, t] +  
vy[x, y, z, t] n(0,1,0,0)[x, y, z, t] + n[x, y, z, t] vy(0,1,0,0)[x, y, z, t] +  
vx[x, y, z, t] n(1,0,0,0)[x, y, z, t] + n[x, y, z, t] vx(1,0,0,0)[x, y, z, t] == 0
```


In[50]=

```
w2["continuity"][3] =
w2["continuity"][2] /. perturbationRules /. equilibriumRules //
LinearizeEquation // ApplyEikonal
```

Out[50]=

$$-\omega \delta \hat{n} + \delta \hat{v}_x k_x n_0 + \delta \hat{v}_y k_y n_0 + \delta \hat{v}_z k_z n_0 == 0$$

In[51]=

```
w2["continuity"][4] = Solve[w2["continuity"][3], δn][[1, 1]] // ExpandAll
```

Out[51]=

$$\delta \hat{n} \rightarrow \frac{\delta \hat{v}_x k_x n_0}{\omega} + \frac{\delta \hat{v}_y k_y n_0}{\omega} + \frac{\delta \hat{v}_z k_z n_0}{\omega}$$

and then the equation of fluid motion

In[52]=

```
w2["motion"][1] =
Inactivate[m n DDt[v, v] == n q (ε + 1/c Cross[v, B]), DDt | Cross | Plus]
```

Out[52]=

$$m n \text{DDt}[v, v] == n q \left(\epsilon + \frac{v \times B}{c} \right)$$

where the functions DDt is defined below to implement the convective derivative $\frac{d}{dt} = \frac{\partial}{\partial t} + v \cdot \nabla$.

Again, this notebook focuses on the calculation. A plasma physics text should be consulted to appreciate the context in which these fluid equations are applicable.

Now that the vector terms have been expanded, it is preferable to rewrite this expression as a list of equations.

In[54]=

```
w2["motion"][2] =
w2["motion"][1] /. {MakeScalar[n], MakeVector[v], MakeVector[ε], MakeVector[B]}
```

Out[54]=

$$m n[x, y, z, t] \text{DDt}[\{v_x[x, y, z, t], v_y[x, y, z, t], v_z[x, y, z, t]\}, \\ \{v_x[x, y, z, t], v_y[x, y, z, t], v_z[x, y, z, t]\}] == \\ q n[x, y, z, t] \left(\{\epsilon_x[x, y, z, t], \epsilon_y[x, y, z, t], \epsilon_z[x, y, z, t]\} + \frac{1}{c} \{v_x[x, y, z, t], \\ v_y[x, y, z, t], v_z[x, y, z, t]\} \times \{B_x[x, y, z, t], B_y[x, y, z, t], B_z[x, y, z, t]\} \right)$$

In[55]:=

w2["motion"][3] = Activate[w2["motion"][2], DDt | Cross]

Out[55]=

$$\left\{ \begin{aligned} & m n[x, y, z, t] \left(v_x^{(0,0,0,1)}[x, y, z, t] + v_x[x, y, z, t] v_x^{(1,0,0,0)}[x, y, z, t] \right), \\ & m n[x, y, z, t] \left(v_y^{(0,0,0,1)}[x, y, z, t] + v_y[x, y, z, t] v_y^{(0,1,0,0)}[x, y, z, t] \right), \\ & m n[x, y, z, t] \left(v_z^{(0,0,0,1)}[x, y, z, t] + v_z[x, y, z, t] v_z^{(0,0,1,0)}[x, y, z, t] \right) \end{aligned} \right\} == \\ q n[x, y, z, t] \left(\left\{ \varepsilon_x[x, y, z, t], \varepsilon_y[x, y, z, t], \varepsilon_z[x, y, z, t] \right\} + \right. \\ \left. \left\{ \frac{1}{c} \left(-v_z[x, y, z, t] \mathcal{B}_y[x, y, z, t] + v_y[x, y, z, t] \mathcal{B}_z[x, y, z, t] \right), \frac{1}{c} \right. \right. \\ \left. \left. \left(v_z[x, y, z, t] \mathcal{B}_x[x, y, z, t] - v_x[x, y, z, t] \mathcal{B}_z[x, y, z, t] \right), \frac{1}{c} \right. \right. \\ \left. \left. \left(-v_y[x, y, z, t] \mathcal{B}_x[x, y, z, t] + v_x[x, y, z, t] \mathcal{B}_y[x, y, z, t] \right) \right\} \right)$$

In[56]:=

w2["motion"][4] = Activate[w2["motion"][3], Plus]

Out[56]=

$$\left\{ \begin{aligned} & m n[x, y, z, t] \left(v_x^{(0,0,0,1)}[x, y, z, t] + v_x[x, y, z, t] v_x^{(1,0,0,0)}[x, y, z, t] \right), \\ & m n[x, y, z, t] \left(v_y^{(0,0,0,1)}[x, y, z, t] + v_y[x, y, z, t] v_y^{(0,1,0,0)}[x, y, z, t] \right), \\ & m n[x, y, z, t] \left(v_z^{(0,0,0,1)}[x, y, z, t] + v_z[x, y, z, t] v_z^{(0,0,1,0)}[x, y, z, t] \right) \end{aligned} \right\} == \\ \left\{ q n[x, y, z, t] \left(\frac{1}{c} \left(-v_z[x, y, z, t] \mathcal{B}_y[x, y, z, t] + v_y[x, y, z, t] \mathcal{B}_z[x, y, z, t] \right) + \right. \right. \\ \left. \left. \varepsilon_x[x, y, z, t] \right), q n[x, y, z, t] \right. \\ \left. \left(\frac{1}{c} \left(v_z[x, y, z, t] \mathcal{B}_x[x, y, z, t] - v_x[x, y, z, t] \mathcal{B}_z[x, y, z, t] \right) + \varepsilon_y[x, y, z, t] \right), q \right. \\ \left. n[x, y, z, t] \right. \\ \left. \left(\frac{1}{c} \left(-v_y[x, y, z, t] \mathcal{B}_x[x, y, z, t] + v_x[x, y, z, t] \mathcal{B}_y[x, y, z, t] \right) + \varepsilon_z[x, y, z, t] \right) \right\}$$

The procedure of activating DDt and Cross before activating Plus is kludgy. The reason is that you need to have the vector expressions expand into lists before they are added. To see the problem try the "motion" calculation without initially inactivating Plus.

In[57]:=

w2["motion"][5] = w2["motion"][4] // GenerateComponentEquations

Out[57]=

$$\left\{ \begin{aligned} & m n[x, y, z, t] v_x^{(0,0,0,1)}[x, y, z, t] + m n[x, y, z, t] v_x[x, y, z, t] v_x^{(1,0,0,0)}[x, y, z, t] == \\ & -\frac{1}{c} q n[x, y, z, t] v_z[x, y, z, t] \mathcal{B}_y[x, y, z, t] + \frac{1}{c} \\ & q n[x, y, z, t] v_y[x, y, z, t] \mathcal{B}_z[x, y, z, t] + q n[x, y, z, t] \varepsilon_x[x, y, z, t], \\ & m n[x, y, z, t] v_y^{(0,0,0,1)}[x, y, z, t] + m n[x, y, z, t] v_y[x, y, z, t] v_y^{(0,1,0,0)}[x, y, z, t] == \\ & \frac{1}{c} q n[x, y, z, t] v_z[x, y, z, t] \mathcal{B}_x[x, y, z, t] - \frac{1}{c} \\ & q n[x, y, z, t] v_x[x, y, z, t] \mathcal{B}_z[x, y, z, t] + q n[x, y, z, t] \varepsilon_y[x, y, z, t], \\ & m n[x, y, z, t] v_z^{(0,0,0,1)}[x, y, z, t] + m n[x, y, z, t] v_z[x, y, z, t] v_z^{(0,0,1,0)}[x, y, z, t] == \\ & -\frac{1}{c} q n[x, y, z, t] v_y[x, y, z, t] \mathcal{B}_x[x, y, z, t] + \frac{1}{c} \\ & q n[x, y, z, t] v_x[x, y, z, t] \mathcal{B}_y[x, y, z, t] + q n[x, y, z, t] \varepsilon_z[x, y, z, t] \end{aligned} \right\}$$

In[58]=

```
w2["motion"][6] =
w2["motion"][5] /. perturbationRules /. equilibriumRules // LinearizeEquation
```

Out[58]=

$$\left\{ \begin{aligned} m n_0 \delta v_x^{(0,0,0,1)}[x, y, z, t] &= \frac{B q n_0 \delta v_y[x, y, z, t]}{c} + q n_0 \delta \varepsilon_x[x, y, z, t], \\ m n_0 \delta v_y^{(0,0,0,1)}[x, y, z, t] &= -\frac{B q n_0 \delta v_x[x, y, z, t]}{c} + q n_0 \delta \varepsilon_y[x, y, z, t], \\ m n_0 \delta v_z^{(0,0,0,1)}[x, y, z, t] &= q n_0 \delta \varepsilon_z[x, y, z, t] \end{aligned} \right\}$$

In[59]=

```
w2["motion"][7] = w2["motion"][6] /. Sol[def[omega_c], B]
```

Out[59]=

$$\left\{ \begin{aligned} m n_0 \delta v_x^{(0,0,0,1)}[x, y, z, t] &= m n_0 \omega_c \delta v_y[x, y, z, t] + q n_0 \delta \varepsilon_x[x, y, z, t], \\ m n_0 \delta v_y^{(0,0,0,1)}[x, y, z, t] &= -m n_0 \omega_c \delta v_x[x, y, z, t] + q n_0 \delta \varepsilon_y[x, y, z, t], \\ m n_0 \delta v_z^{(0,0,0,1)}[x, y, z, t] &= q n_0 \delta \varepsilon_z[x, y, z, t] \end{aligned} \right\}$$

In[60]=

```
w2["motion"][8] = w2["motion"][7] // ApplyEikonal
```

Out[60]=

$$\left\{ \begin{aligned} -m \omega \delta \hat{v}_x n_0 &= -i q \delta \hat{\varepsilon}_x n_0 - i m \delta \hat{v}_y n_0 \omega_c, \\ -m \omega \delta \hat{v}_y n_0 &= -i q \delta \hat{\varepsilon}_y n_0 + i m \delta \hat{v}_x n_0 \omega_c, \\ -m \omega \delta \hat{v}_z n_0 &= -i q \delta \hat{\varepsilon}_z n_0 \end{aligned} \right\}$$

In[61]=

```
w2["motion"][9] = Solve[w2["motion"][8], {\delta\hat{v}_x, \delta\hat{v}_y, \delta\hat{v}_z}][[1]] // ExpandAll
```

Out[61]=

$$\left\{ \begin{aligned} \delta \hat{v}_x &\rightarrow \frac{i q \omega \delta \hat{\varepsilon}_x}{m \omega^2 - m \omega_c^2} - \frac{q \delta \hat{\varepsilon}_y \omega_c}{m \omega^2 - m \omega_c^2}, \quad \delta \hat{v}_y \rightarrow \frac{i q \omega \delta \hat{\varepsilon}_y}{m \omega^2 - m \omega_c^2} + \frac{q \delta \hat{\varepsilon}_x \omega_c}{m \omega^2 - m \omega_c^2}, \quad \delta \hat{v}_z \rightarrow \frac{i q \delta \hat{\varepsilon}_z}{m \omega} \end{aligned} \right\}$$

The perturbed velocities are

In[62]=

```
w2["motion"][9] // ColumnForm
```

Out[62]=

$$\left\{ \begin{aligned} \delta \hat{v}_x &\rightarrow \frac{i q \omega \delta \hat{\varepsilon}_x}{m \omega^2 - m \omega_c^2} - \frac{q \delta \hat{\varepsilon}_y \omega_c}{m \omega^2 - m \omega_c^2} \\ \delta \hat{v}_y &\rightarrow \frac{i q \omega \delta \hat{\varepsilon}_y}{m \omega^2 - m \omega_c^2} + \frac{q \delta \hat{\varepsilon}_x \omega_c}{m \omega^2 - m \omega_c^2} \\ \delta \hat{v}_z &\rightarrow \frac{i q \delta \hat{\varepsilon}_z}{m \omega} \end{aligned} \right\}$$

The current density is

In[63]=

```
w2["current density"][1] = q n_0 {\delta\hat{v}_x, \delta\hat{v}_y, \delta\hat{v}_z} /. w2["motion"][9]
```

Out[63]=

$$\left\{ q n_0 \left(\frac{i q \omega \delta \hat{\varepsilon}_x}{m \omega^2 - m \omega_c^2} - \frac{q \delta \hat{\varepsilon}_y \omega_c}{m \omega^2 - m \omega_c^2} \right), q n_0 \left(\frac{i q \omega \delta \hat{\varepsilon}_y}{m \omega^2 - m \omega_c^2} + \frac{q \delta \hat{\varepsilon}_x \omega_c}{m \omega^2 - m \omega_c^2} \right), \frac{i q^2 \delta \hat{\varepsilon}_z n_0}{m \omega} \right\}$$

The conductivity tensor is

In[64]:=
$$\mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][1] = \frac{4\pi\mathbf{I}}{\omega}\mathbf{w2}[\text{"current density"}][1]$$

Out[64]=
$$\left\{\frac{1}{\omega}4\pi\mathbf{q}n_0\left(\frac{\mathbf{i}q\omega\delta\hat{\epsilon}_x}{m\omega^2 - m\omega_c^2} - \frac{q\delta\hat{\epsilon}_y\omega_c}{m\omega^2 - m\omega_c^2}\right), \frac{1}{\omega}4\pi\mathbf{q}n_0\left(\frac{\mathbf{i}q\omega\delta\hat{\epsilon}_y}{m\omega^2 - m\omega_c^2} + \frac{q\delta\hat{\epsilon}_x\omega_c}{m\omega^2 - m\omega_c^2}\right), -\frac{4\pi\mathbf{q}^2\delta\hat{\epsilon}_z n_0}{m\omega^2}\right\}$$

In[66]:=
$$\mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][2] = \mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][1] /. \text{Sol}[\text{def}[\omega_p], n_0] // \text{Simplify} // \text{ExpandAll}$$

Out[66]=
$$\left\{-\frac{\omega\delta\hat{\epsilon}_x\omega_p^2}{\omega^3 - \omega\omega_c^2} - \frac{\mathbf{i}\delta\hat{\epsilon}_y\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, -\frac{\omega\delta\hat{\epsilon}_y\omega_p^2}{\omega^3 - \omega\omega_c^2} + \frac{\mathbf{i}\delta\hat{\epsilon}_x\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, -\frac{\delta\hat{\epsilon}_z\omega_p^2}{\omega^2}\right\}$$

In[67]:=
$$\mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][3] = \text{Table}[\text{Table}[\text{Coefficient}[\mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][2][[i]], \text{component}], \{\text{component}, \{\delta\hat{\epsilon}_x, \delta\hat{\epsilon}_y, \delta\hat{\epsilon}_z\}\}], \{i, 1, 3\}]$$

Out[67]=
$$\left\{\left\{-\frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2}, -\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, \mathbf{0}\right\}, \left\{\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, -\frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2}, \mathbf{0}\right\}, \left\{\mathbf{0}, \mathbf{0}, -\frac{\omega_p^2}{\omega^2}\right\}\right\}$$

In[68]:=
$$\mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][3] // \text{MatrixForm}$$

Out[68]/MatrixForm=

$$\begin{pmatrix} -\frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2} & -\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2} & \mathbf{0} \\ \frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2} & -\frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & -\frac{\omega_p^2}{\omega^2} \end{pmatrix}$$

The dielectric tensor is

In[69]:=
$$\mathbf{w2}[\text{"dielectric tensor"}][1] = \text{IdentityMatrix}[3] + \mathbf{w2}\left[\frac{4\pi\mathbf{i}}{\omega}\right][3]$$

Out[69]=
$$\left\{\left\{1 - \frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2}, -\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, \mathbf{0}\right\}, \left\{\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2}, 1 - \frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2}, \mathbf{0}\right\}, \left\{\mathbf{0}, \mathbf{0}, 1 - \frac{\omega_p^2}{\omega^2}\right\}\right\}$$

In[70]:=
$$\mathbf{w2}[\text{"dielectric tensor"}][1] // \text{MatrixForm}$$

Out[70]/MatrixForm=

$$\begin{pmatrix} 1 - \frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2} & -\frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2} & \mathbf{0} \\ \frac{\mathbf{i}\omega_c\omega_p^2}{\omega^3 - \omega\omega_c^2} & 1 - \frac{\omega\omega_p^2}{\omega^3 - \omega\omega_c^2} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & 1 - \frac{\omega_p^2}{\omega^2} \end{pmatrix}$$

and the specific form for the dielectric tensor has been obtained.

Functions

The following are functions that facilitate the handling of vector expressions.

```
In[7]:= Clear[MakeScalar, MakeVector];
(* These functions implement rules that transform a symbol in to a
   scalar or vector form that included explicit space-time dependence *)
MakeScalar[arg_] := arg → arg[x, y, z, t];
(* using x,y,z for vector components and x, y,
   z for variables simplifies some pattern matching operations *)
MakeVector[arg_] := arg → {argx[x, y, z, t], argy[x, y, z, t], argz[x, y, z, t]};
(* Handles the case of "vectoring" the time derivative of a vector quantity *)
MakeVector[Inactive[D[arg_, t], D]] :=
  Inactive[D[arg, t], D] → {Inactive[D[argx[x, y, z, t], t], D],
    Inactive[D[argy[x, y, z, t], t], D], Inactive[D[argz[x, y, z, t], t], D]}
```

```
In[7]:= Clear[GenerateComponentEquations];
(* This transforms {a, b, c} == {d, e, f} to {a==c,b==d,c==e} *)
GenerateComponentEquations[lhsList_ = rhsList_] :=
  Thread[Equal[ExpandAll[lhsList], ExpandAll[rhsList]]]
```

Convective derivative: The functions *DDt* and *vDel* implement the convective derivative

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla$$

```
In[9]:= Clear[DDt];
DDt[{vx_, vy_, vz_}, {fx_, fy_, fz_}] :=
  D[{fx, fy, fz}, t] + vDel[{vx, vy, vz}, {fx, fy, fz}];
DDt[{vx_, vy_, vz_}, f_] := D[f, t] + vDel[{vx, vy, vz}, f];
```

```
In[12]:= Clear[vDel];
vDel[{vx_, vy_, vz_}, f_] :=
  vx D[f, x] + vy D[f, y] + vz D[f, z];
vDel[{vx_, vy_, vz_}, {fx_, fy_, fz_}] :=
  {vx D[fx, x], vy D[fy, y], vz D[fz, z]}
```

perturbation rules: I define some rules that will be used to perturb the fluid equations

In[15]=

```

perturbationRules =
{ n → ((n0 + ε δn[#1, #2, #3, #4]) &),
  vx → ((vx0 + ε δvx[#1, #2, #3, #4]) &),
  vy → ((vy0 + ε δvy[#1, #2, #3, #4]) &),
  vz → ((vz0 + ε δvz[#1, #2, #3, #4]) &),
  jx → ((jx0 + ε δjx[#1, #2, #3, #4]) &),
  jy → ((jy0 + ε δjy[#1, #2, #3, #4]) &),
  jz → ((jz0 + ε δjz[#1, #2, #3, #4]) &),
  εx → ((εx0 + ε δεx[#1, #2, #3, #4]) &),
  εy → ((εy0 + ε δεy[#1, #2, #3, #4]) &),
  εz → ((εz0 + ε δεz[#1, #2, #3, #4]) &),
  Bx → ((Bx0 + ε δBx[#1, #2, #3, #4]) &),
  By → ((By0 + ε δBy[#1, #2, #3, #4]) &),
  Bz → ((Bz0 + ε δBz[#1, #2, #3, #4]) &)};

```

equilibriumRules: I introduce specific rules that describe the equilibrium — homogeneous density $n_0 =$ constant, no flows $\vec{v}_0 = 0$, no equilibrium electric field $\vec{\mathcal{E}}_0 = 0$, uniform equilibrium magnetic field $\vec{\mathcal{B}}_0 = \mathcal{B}_0 \vec{1}_z$.

In[16]=

```

equilibriumRules =
{vx0 → 0, vy0 → 0, vz0 → 0, jx0 → 0, jy0 → 0, jz0 → 0, εx0 → 0, εy0 → 0, εz0 → 0,
  Bx0 → 0, By0 → 0, Bz0 → B}

```

Out[16]=

```

{vx0 → 0, vy0 → 0, vz0 → 0, jx0 → 0, jy0 → 0,
  jz0 → 0, εx0 → 0, εy0 → 0, εz0 → 0, Bx0 → 0, By0 → 0, Bz0 → B}

```

I define the following function for linearizing an equation

In[17]=

```

Clear[LinearizeEquation];
LinearizeEquation[lhs_ == rhs_] :=
  Coefficient[ExpandAll[lhs], ε] == Coefficient[ExpandAll[rhs], ε];
LinearizeEquation[eqnList_List] := LinearizeEquation /@ eqnList;

```

I introduce a plane wave eikonal form for the solutions and some tools for simplifying expressions that arise when this solution type is assumed.

In[20]:=

```

Clear[Eikonal, MakeEikonalRule, ApplyEikonal];
Eikonal[x_, y_, z_, t_] := Exp[I k_x x + I k_y y + I k_z z - I ω t];
MakeEikonalRule[var_[x_, y_, z_, t_]] :=
  var → Function[{x, y, z, t}, v̂r Eikonal[x, y, z, t]];
eikonalRules = MakeEikonalRule /@ {δε_x[x, y, z, t],
  δε_y[x, y, z, t], δε_z[x, y, z, t], δB_x[x, y, z, t], δB_y[x, y, z, t],
  δB_z[x, y, z, t], δv_x[x, y, z, t], δv_y[x, y, z, t], δv_z[x, y, z, t],
  δj_x[x, y, z, t], δj_y[x, y, z, t], δj_z[x, y, z, t], δn[x, y, z, t]};
eikonalTerm = Eikonal[x, y, z, t];
ApplyEikonal[eqn_] :=
  Module[{step},
    step[1] = eqn /. eikonalRules;
    step[2] = MapEqn[ (# / (I eikonalTerm)) &, step[1]] // ExpandAll];
ApplyEikonal[eqnList_List] := ApplyEikonal /@ eqnList;

```

Introduce the gyrofrequency and plasma frequency

In[26]:=

```

def[ω_c] = ω_c ==  $\frac{q B}{m c}$ ;
def[ω_p] = ω_p^2 ==  $\frac{4 \pi q^2 n_0}{m}$ ;

```

Visualization

The magnetized plasma geometry and wave vector

```

Module[{0, ex, ey, ez, Bvec, kVec, T, Vec, G = Graphics3D},
  T[text_, position_] := Text[Style[text, Bold, FontSize -> 10], position];
  Vec[vec_] := {Arrowheads[0.05], Arrow[Tube[vec, 0.02]]};
  {0, ex, ey, ez} = {{0, 0, 0}, {1, 0, 0}, {0, 1, 0}, {0, 0, 1}};
  Bvec = {Blue, Vec[{0, 0.75 ez}], T[" $\vec{B} = B e_z$ ", 0.8 ez]};
  kVec =
    {Red, Vec[{0, 0.75 {0.1, 1, 1}], T[" $\vec{k} = k_x e_x + k_y e_y + k_z e_z$ ", 0.8 {0.1, 1, 1}]}];

  Show[
    G[{{Gray, Arrow[{0, ex}], {Gray, Arrow[{0, ey}]},
      {Gray, Arrow[{0, ez}], {Bvec, kVec}}, Boxed -> False},
    G[{T["x", 1.1 ex], T["y", 1.1 ey], T["z", 1.1 ez]}],

    PlotRange -> {{-0.4, 1.4}, {-0.4, 1.4}, {0, 1.4}},
    ViewPoint -> {2, 2, 1}, ImageSize -> {350, 350}, SphericalRegion -> True,
    PlotLabel -> St1["Equilibrium plasma geometry"]]

```

Equilibrium plasma geometry

