

BenderOrszag Ex1p241 03-31-16

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Initialization: Be sure the files *NTGStylesheet2.nb* and *NTGUtilityFunctions.m* are in the same directory as that from which this notebook was loaded. Then execute the cell immediately below by mousing left on the cell bar to the right of that cell and then typing “shift” + “enter”. Respond “Yes” in response to the query to evaluate initialization cells.

```
In[7]:= SetDirectory[NotebookDirectory[]];
(* set directory where source files are located *)
SetOptions[EvaluationNotebook[], (* load the StyleSheet *)
  StyleDefinitions -> Get["NTGStylesheet2.nb"]];
Get["NTGUtilityFunctions.m"]; (* Load utilities package *)
```

Cleaned up version of work originally performed in *BenderOrszag Ex1p241 09-12-15*

Purpose

Section 6.6 of Bender and Orszag deals with evaluation of an integral using the method of steepest descent. Given an integral of the form

$$\mathcal{I}(k) = \int_C dz h(z) e^{k\rho(z)}$$

the idea of steepest descent is deform the contour so that the integral can be approximated by

$$\mathcal{I}(k) = \int_C dz h(z) e^{k(\rho_R(z) + i\rho_I(z))} \simeq e^{ik\rho_I} \int_{C_{\text{deformed}}} dz h(z) e^{k\rho_R(z)}$$

In words, a contour is sought along which the imaginary part of $\rho(z)$ is approximately constant. Under such circumstances the integrand is localized and as well as not highly oscillatory at large k .

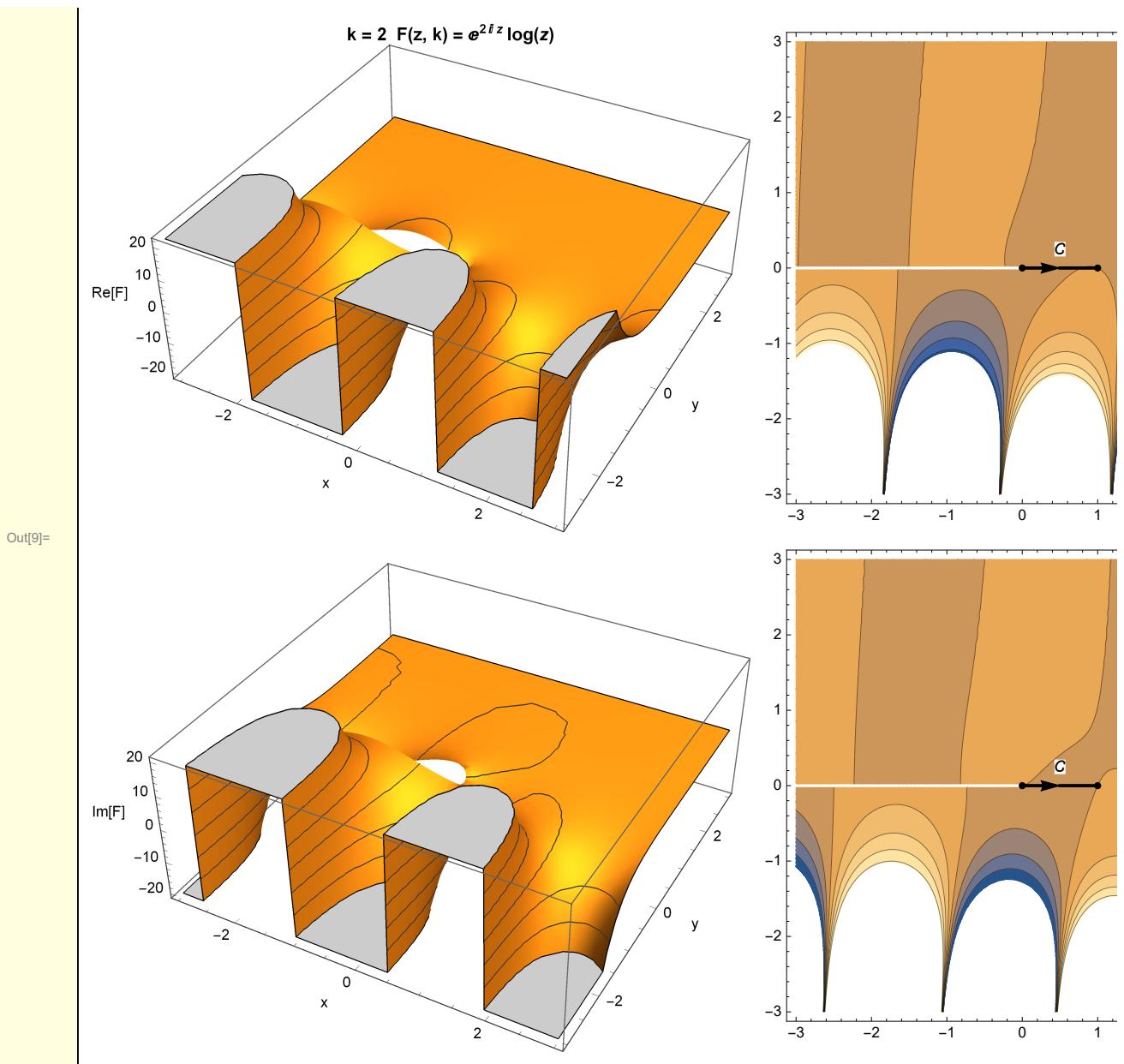
Example 1, p241 of Bender and Orszag considers valuation of

$$\mathcal{I}(k) = \int_0^1 \ln(z) e^{ikz} dz$$

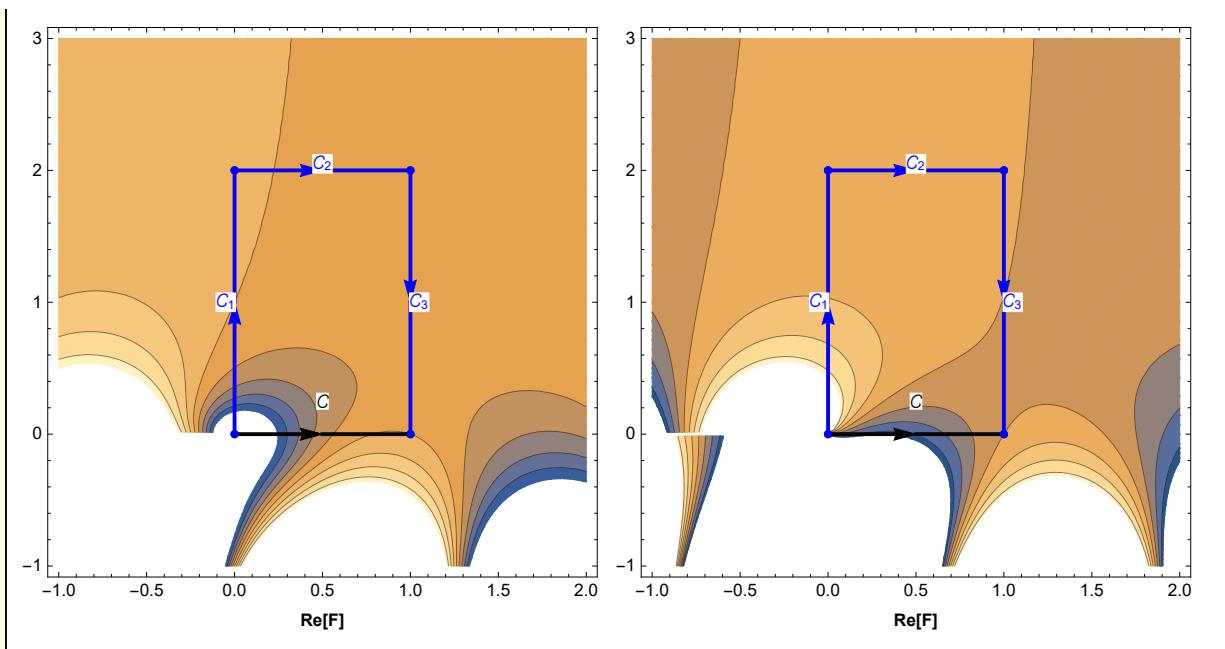
After working through this calculation with pen and paper, I perform the calculation using *Mathematica* and provide some visualizations.

I begin with some visualizations of the function over which the integration is performed.

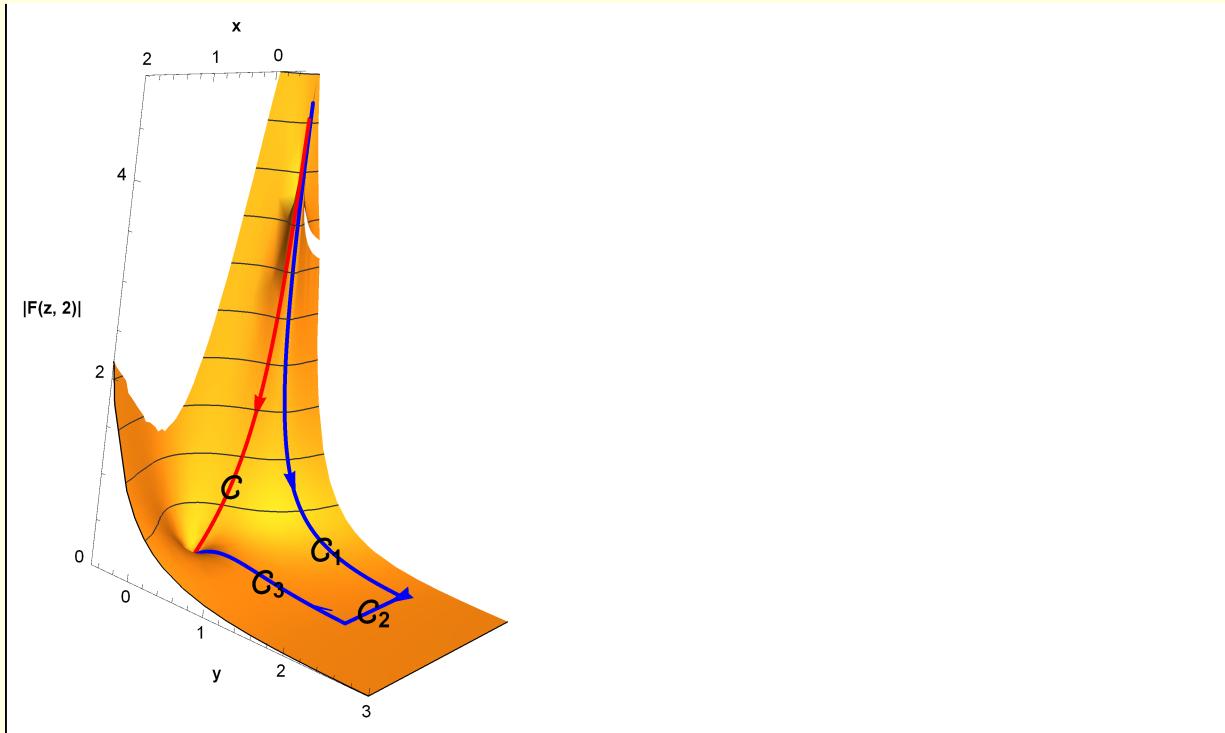
Note the branch cut associated with \log and the poles associated with $\exp[i k z]$ for $z_{\text{Im}} < 0$



$\mathcal{I}(k)$ is evaluated by contour integration. The contour C $(0,0) \rightarrow (1, 0)$ is deformed into C_1 $(0,0) \rightarrow (0, i Y) + C_2$ $(0, i Y) \rightarrow (1, i Y) + C_3$ $(1, i Y) \rightarrow (0, i Y)$. Note that C_1 and C_3 are along line of constant phase $\{x, y\} = r e^{i\pi/2}$



It is instructive to view a 3-D representation of the integration path



Analysis

I develop analytical approximations for the integrations along contours C_1 , C_2 , C_3 .

| C_1

Along contour C_1 the integrand is

```
In[13]:= w1[1] =
  Log[z] Exp[I k z] dz /. z → 0 + I y /. dz → I dy /. dy → 1 // PowerExpand // Expand

Out[13]= - 1/2 e-ky π + i e-ky Log[y]
```

I use a constructed function *Int* (rather than Mathematica's *Integrate*) to temporarily suppress evaluation of the integral while manipulations are performed. After manipulations have been completed, evaluation can be triggered by setting *Int* → *Integrate*. There is a slight complication in that *Integrate* is designed for integration on the real line and the concern here is with contour integrals. Note that I explicitly introduce a differential form *dz* for the variable of integration *z*, and define it appropriately for the contour being handled. This insures that any complex phase factor has been properly incorporated in the calculation. For example, a contour along the real axis would have *dz* → *dx* and a contour along the imaginary axis would have *dz* → *I dy*. Finally, since *Integrate* does not require explicit mention of the differential *dx* or *dy*, I set them to unity.

```
In[14]:= w1[2] = Int[w1[1], {y, 0, Y}] // . IntRules

Out[14]= - 1/2 π Int[e-ky, {y, 0, Y}] + i Int[e-ky Log[y], {y, 0, Y}]
```

where simplifying rules *IntRules* are defined below.

Take the limit $Y \rightarrow \infty$

```
In[15]:= w1[3] = w1[2] /. Y → ∞

Out[15]= - 1/2 π Int[e-ky, {y, 0, ∞}] + i Int[e-ky Log[y], {y, 0, ∞}]
```

```
In[16]:= w1[4] =
  (w1[3][1] /. Int → Integrate // Simplify[#, {k ∈ Reals, k > 0}] &) + w1[3][2]

Out[16]= - π/(2 k) + i Int[e-ky Log[y], {y, 0, ∞}]
```

Evaluating the integral

```
In[17]:= w1["final"] =
  w1[4] /. Int → Integrate // Simplify[#, {k ∈ Reals, k > 0}] & // Expand

Out[17]= - i EulerGamma/k - π/(2 k) - i Log[k]/k
```

```
In[18]:= QuickCheck[NIntegrate[w1[1] /. k → 3, {y, 0, ∞}], w1["final"] /. k → 3]
```

Check

numerical	approximate	difference
-0.523599 - 0.558609 i	-0.523599 - 0.558609 i	2.40461 × 10 ⁻¹²

2 C_2

Along this contour the integrand is

```
In[19]:= w2[1] = Log[z] Exp[I k z] dz /. z → x + I Y /. dz → dx /. dx → 1 // ExpandAll
Out[19]= ei k x - k Y Log[x + i Y]
```

As $Y \rightarrow \infty$, the integrand tends to 0 and the contribution from this integral is 0

```
In[20]:= w2[2] = Limit[w2[1], Y → ∞, Assumptions → {k > 0}]
Out[20]= 0
```

```
In[21]:= w2["final"] = w2[2]
Out[21]= 0
```

3 C_3

```
In[22]:= w3[1] = Log[z] Exp[I k z] dz /. z → 1 + I y /. dz → I dy /. dy → 1 // ExpandAll
Out[22]= i ei k - k y Log[1 + i y]
```

This integral is approximated by expanding the logarithm and performing term by term integration

```
In[23]:= w3[2] = Series[Log[1 + i y], {y, 0, 5}] // Normal
Out[23]= i y +  $\frac{y^2}{2} - \frac{i y^3}{3} - \frac{y^4}{4} + \frac{i y^5}{5}$ 
```

```
In[24]:= w3[3] = w3[1] /. Log[1 + I y] → w3[2]
Out[24]= i ei k - k y  $\left( i y + \frac{y^2}{2} - \frac{i y^3}{3} - \frac{y^4}{4} + \frac{i y^5}{5} \right)$ 
```

```
In[25]:= w3[4] = Int[w3[3] // Expand, {y, ∞, 0}] // IntRules
Out[25]= -Int[e^(i k - k y) y, {y, ∞, 0}] + 1/2 I Int[e^(i k - k y) y^2, {y, ∞, 0}] +
1/3 Int[e^(i k - k y) y^3, {y, ∞, 0}] - 1/4 I Int[e^(i k - k y) y^4, {y, ∞, 0}] - 1/5 I Int[e^(i k - k y) y^5, {y, ∞, 0}]
```

```
In[26]:= w3[5] = w3[4] /. Int → Integrate // Simplify[#, {k ∈ Reals, k > 0}] & // Expand
Out[26]= 24 e^(i k)/k^6 + 6 I e^(i k)/k^5 - 2 e^(i k)/k^4 - I e^(i k)/k^3 + e^(i k)/k^2
```

```
In[27]:= QuickCheck[NIntegrate[w3[1] /. k → 5, {y, ∞, 0}], w3[5] /. k → 5]
          Check
Out[27]= 

| numerical                | approximate             | difference  |
|--------------------------|-------------------------|-------------|
| 0.00417302 - 0.0380059 I | 0.00504421 - 0.038486 I | 0.000994696 |


```

Simplify so that a pattern can be detected

```
In[28]:= w3[6] = (# term) & /@ w3[5] /. term → k^2 / Exp[I k]
Out[28]= 1 + 24/k^4 + 6 I/k^3 - 2/k^2 - I/k
```

I can see the general pattern

```
In[29]:= Table[(-I)^n n!, {n, 0, 4}]
Out[29]= {1, -I/k, -2/k^2, 6 I/k^3, 24/k^4}
```

and check that this is correct

```
In[30]:= w3[7] = (1/term Sum[(-I)^n n!, {n, 0, 4}] /. term → k^2 / Exp[I k]) - w3[5] // ExpandAll
Out[30]= 0
```

```
In[31]:= w3["final"] = 1/term sum[(-I)^n n!, {n, 0, N}] /. term → k^2 / Exp[I k]
Out[31]= e^(i k) sum[((-I)^n k^-n n!), {n, 0, N}]/k^2
```

```
In[32]:= QuickCheck[NIntegrate[w3[1] /. k → 5, {y, ∞, 0}] /. k → 5,
w3["final"] /. k → 5 /. N → 5 /. sum → Sum]
```

Check

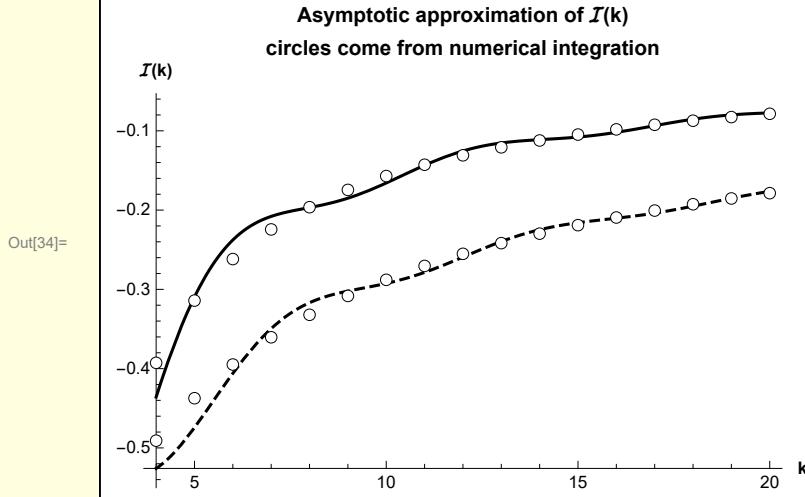
numerical	approximate	difference
0.00417302 - 0.0380059 i	0.00357131 - 0.0389217 i	0.00109574

4 Combining the contributions from the three contours and checking against numerical integration

```
In[33]:= w4[1] = w1["final"] + w2["final"] + w3["final"]
```

$$\text{Out[33]= } -\frac{\frac{i \pi}{2} \text{EulerGamma}}{k} - \frac{\pi}{2 k} - \frac{i \log(k)}{k} + \frac{e^{i k} \sum \left[(-i)^n k^{-n} n!, \{n, 0, N\} \right]}{k^2}$$

```
In[34]:= Module[{Y = 10, N = 3, kMin = 4, kMax = 20,
  numericalValues, points, Inumerical, Ianalytical, lab},
  Inumerical[k_] :=
    NIntegrate[Log[z] Exp[I k z] dz /. z → I y /. dz → I dy /. dy → 1, {y, 0, Y}] +
    NIntegrate[Log[z] Exp[I k z] /. z → x + I Y /. dz → dx /. dx → 1, {x, 0, 1}] +
    NIntegrate[Log[z] Exp[I k z] /. z → 1 + I Y /. dz → I dy /. dy → 1, {y, Y, 0}];
  Ianalytical[k_] := - $\frac{i \text{EulerGamma}}{k} - \frac{\pi}{2k} - \frac{i \log[k]}{k} + \frac{1}{k^2} e^{ik} \sum_{n=0}^N (-i)^n k^{-n} n!$ ;
  numericalValues =
    Table[{k, Re[Inumerical[k]], Im[Inumerical[k]]}, {k, kMin, kMax, 1}];
  lab =
    Stl["Asymptotic approximation of  $I(k)$ \ncircles come from numerical integration"];
  Plot[{Re[Ianalytical[k]], Im[Ianalytical[k]]}, {k, kMin, kMax},
    PlotStyle → {Black, Directive[Black, Dashed]},
    AxesLabel → {Stl["k"], Stl[" $I(k)$ "]},
    Epilog → {OC[#, Black] & /@ numericalValues [[All, {1, 2}]],
      OC[#, Black] & /@ numericalValues[[All, {1, 3}]]}, PlotLabel → lab]
```



Functions

Int is a convenience function for manipulating integral. *IntRules* are some rewrite rules for simplifying *Int[...]*.

```
In[3]:= Clear[IntRules];
IntRules =
  (* Make Int Associative*) {Int[a_ + b_, {var_, lowerLim_, upperLim_}] →
    Int[a, {var, lowerLim, upperLim}] + Int[b, {var, lowerLim, upperLim}],
  (* Make Int transparent to terms free of the integration variable *)
  Int[a_. b_, {var_, lowerLim_, upperLim_}] /; FreeQ[a, var] →
    a Int[b, {var, lowerLim, upperLim}]};
```

QuickCheck is a convenience function for checking that an error has not occurred during a sequence of

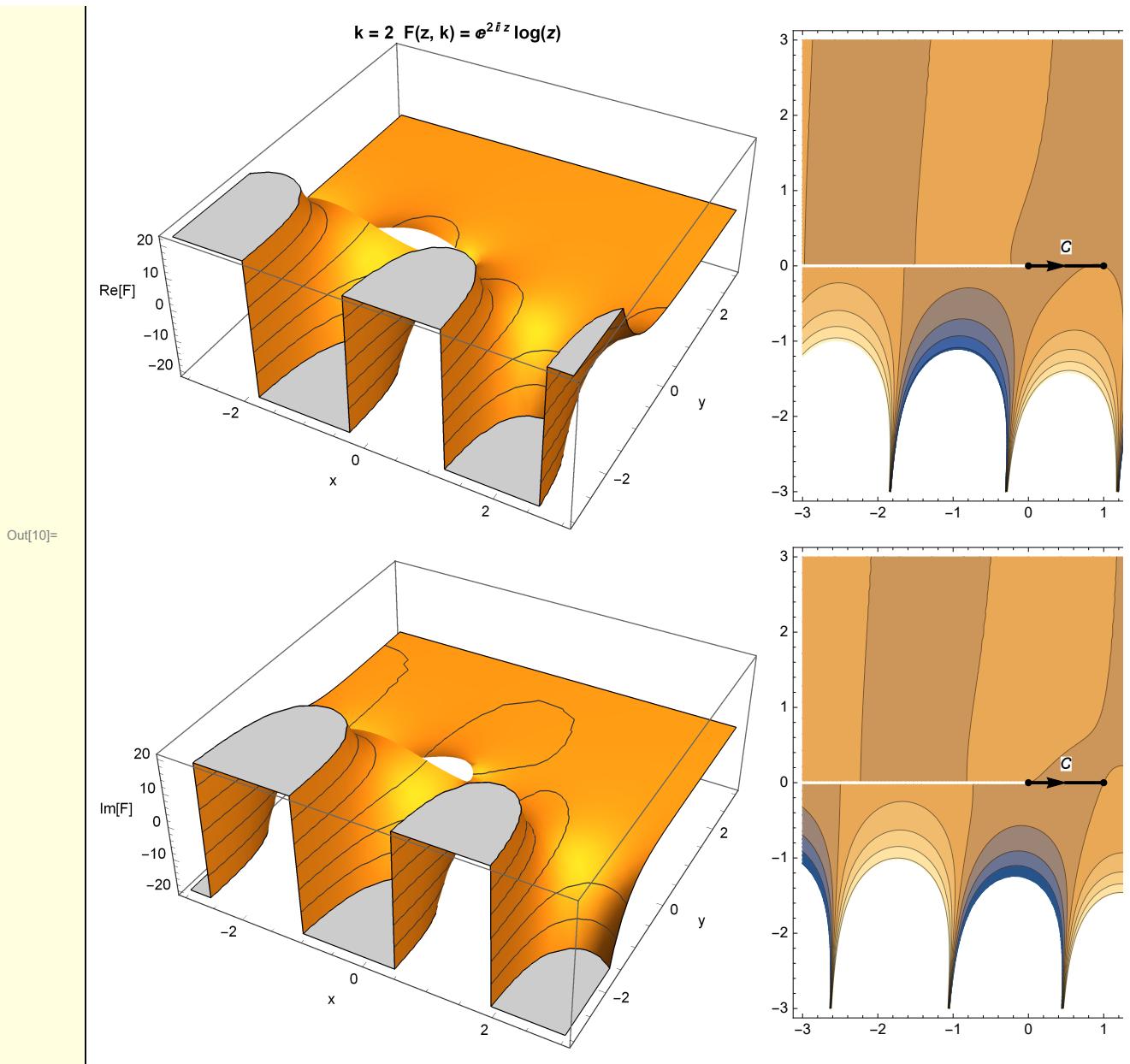
intermediate calculations.

```
In[5]:= Clear[QuickCheck];
QuickCheck[numericalIntegral_, approximateIntegral_] :=
Module[{num, approx, info, diff},
num = numericalIntegral;
approx = approximateIntegral // N;
diff = Abs[num - approx];
info = LGrid[
{{"numerical", "approximate", "|difference|"}, {num, approx, diff}}, "Check"]]
```

Graphics

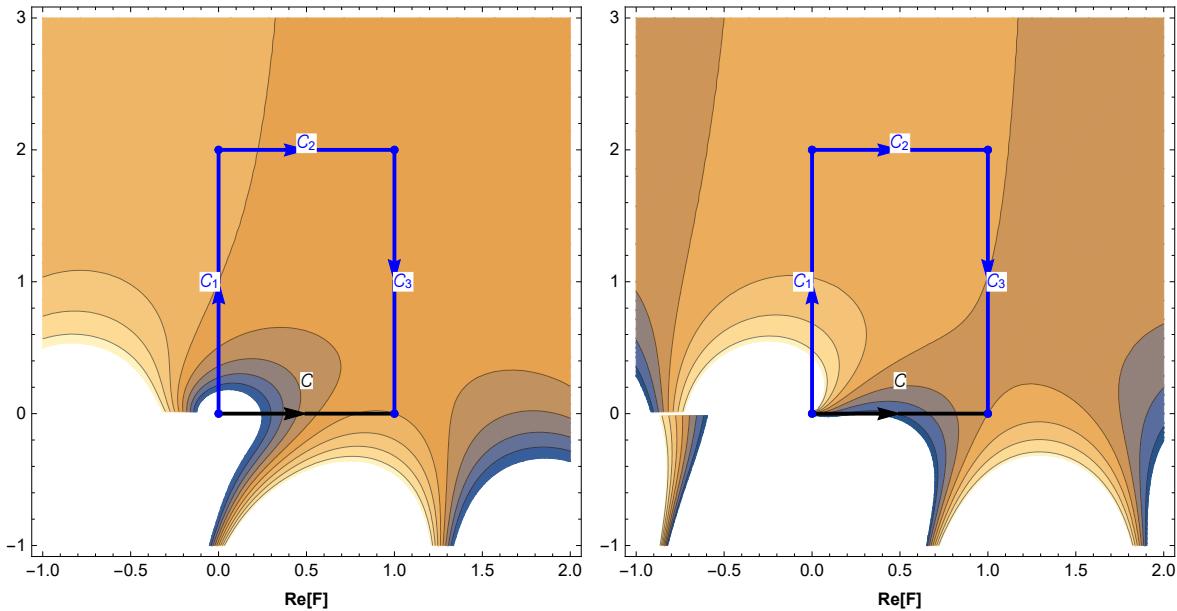
```
In[10]:= Module[{k = 2, imageSize = 400, lab, C, g, F, DirectiveList, CArrow},
F[z_, k_] := Log[z] Exp[I k z];
DirectiveList[plotLabel_, {xLabel_, yLabel_, zLabel_}] :=
Sequence[PlotLabel → plotLabel, AxesLabel → {xLabel, yLabel, zLabel },
ImageSize → imageSize, MeshFunctions → {#3 &}, Mesh → 5];
CArrow[{p1_, p2_}, {lab_, offset_}] :=
{PointSize[0.015], Point[p1], Point[p2], Arrow[{p1, (p1 + p2) / 2}],
Line[{(p1 + p2) / 2, p2}], Style[Text[lab, offset + p1 + (p2 - p1) / 2], Small]};

lab =
Stl@StringForm["k = `` F(z, k) = ``", k, TraditionalForm[Log[z] Exp[I k z]]];
C = {BLACK, CArrow[{{0, 0}, {1, 0}}, {Stl["C"], {0, 0.25}}]};
g[1] = Plot3D[Re[F[x + I y, k]], {x, -3, 3},
{y, -3, 3}, Evaluate[DirectiveList[lab, {"x", "y", "Re[F]"}]]];
g[2] = ContourPlot[Re[F[x + I y, k]], {x, -3, 3}, {y, -3, 3},
AxesLabel → {"x", "y", ""}, ImageSize → 300, Epilog → C];
g[3] = Plot3D[Im[F[x + I y, k]], {x, -3, 3}, {y, -3, 3},
Evaluate[DirectiveList["", {"x", "y", "Im[F]"}]]];
g[4] = ContourPlot[Im[F[x + I y, k]], {x, -3, 3}, {y, -3, 3},
AxesLabel → {"x", "y", ""}, ImageSize → 300, Epilog → C];
Grid[{{g[1], g[2]}, {g[3], g[4]}}]]
```



```
In[11]:= Module[{k = 2, Y = 2, image = 300, g, C, C1, C2, C3, F, CArrow},
F[z_, k_] := Log[z] Exp[I k z];
CArrow[{p1_, p2_}, {lab_, offset_}] :=
{PointSize[0.015], Point[p1], Point[p2], Arrow[{p1, (p1 + p2)/2}],
Line[{(p1 + p2)/2, p2}], Style[Text[lab, offset + p1 + (p2 - p1)/2], Small]};
C = {BLACK, CArrow[{{0, 0}, {1, 0}}, {"C", {0, 0.25}}]}];
C1 = {BLUE, CArrow[{{0, 0}, {0, Y}}, {"C1", {-0.05, 0}}]}];
C2 = {BLUE, CArrow[{{0, Y}, {1, Y}}, {"C2", {0, 0.05}}]}];
C3 = {BLUE, CArrow[{{1, Y}, {1, 0}}, {"C3", {0.05, 0}}]}];
g[1] = ContourPlot[Re[F[x + I y, k]], {x, -1, 2}, {y, -1, 3},
AxesLabel -> {"x", "y", ""}, ImageSize -> image,
Epilog -> {C, C1, C2, C3}, FrameLabel -> Stl["Re[F]"]];
g[2] = ContourPlot[Im[F[x + I y, k]], {x, -1, 2}, {y, -1, 3},
AxesLabel -> {"x", "y", ""}, ImageSize -> image,
Epilog -> {C, C1, C2, C3}, FrameLabel -> Stl["Re[F]"]];
Grid[{{g[1], g[2]}]]]
```

Out[11]=



```
In[12]:= Module[{k = 2, Y = 2, imageSize = 300, lab, g, C, C1, C2,
  C3, gCurve, curve, surface, F, PointOnContour, ContourPath3D},
  F[z_, k_] := Log[z] Exp[I k z];
  PointOnContour[x_, y_, k_] :=
    {x, y, Abs[F[x + I y, k]] + 0.01};
  ContourPath3D[points_, text_] :=
    Module[{n = Length@points, nStart, nFin, nMid, arrow, txt},
      {nStart, nFin} = {Round[0.2 n], Round[0.25 n]};
      nMid = Round[0.5 n];
      arrow = Arrow[{points[[nStart]], points[[nFin]]}];
      txt = Text[text, points[[nMid]]];
      {Line[points], arrow, txt}];

  lab = Stl[StringForm["|F(z, ``)|", k]];
  C = ContourPath3D[
    Table[PointOnContour[x, 0, k], {x, 0.01, 1, 0.01}], Style["C", 16, Bold, Black]];
  C1 = ContourPath3D[Table[PointOnContour[0, y, k], {y, 0.01, 2, 0.01}],
    Style["C1", 16, Bold, Black]];
  C2 = ContourPath3D[Table[PointOnContour[x, 2, k], {x, 0.01, 1, 0.01}],
    Style["C2", 16, Bold, Black]];
  C3 = ContourPath3D[Table[PointOnContour[1, y, k], {y, 2, 0.01, -0.01}],
    Style["C3", 16, Bold, Black]];
  gCurve = Graphics3D[{RED, C}, {BLUE, C1, C2, C3}],
  PlotRange -> {{-0.5, 2}, {-0.5, 3}, {0, 5}}, Axes -> Automatic,
  AxesLabel -> {Stl["x"], Stl["y"], lab}, ImageSize -> imageSize, Boxed -> False];
  surface = Plot3D[Abs[F[x + I y, k]], {x, -1, 2}, {y, -1, 3},
    ImageSize -> imageSize, MeshFunctions -> {#3 &}, Mesh -> 10, Boxed -> False];
  Show[{gCurve, surface}]]
```

